

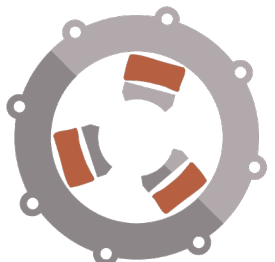
# Oil-Free, Bearingless Motors

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July 30, 2025



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MECHANICAL ENGINEERING

UNIVERSITY OF MINNESOTA

# Problem: Bearings Limit Electrically-Driven Turbomachinery

## Process Compatibility

### Oil/Grease

Ball



Source: SKF

Journal



Source: Miba

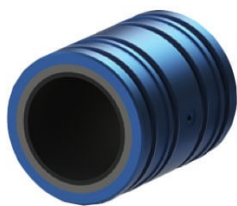
### Oil-Free

Gas Foil



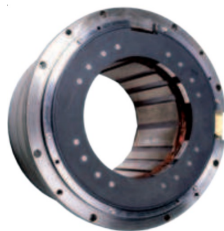
Source: Sulzer

Externally Pressurized



Source: Isotech

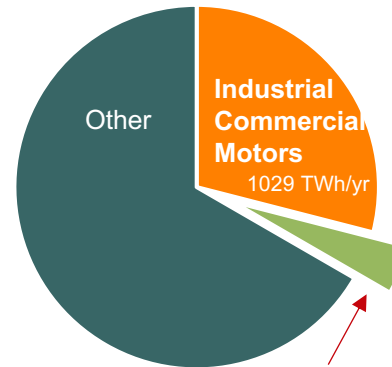
Magnetic



Source: S2M

## Low Efficiency

US Electricity Consumption



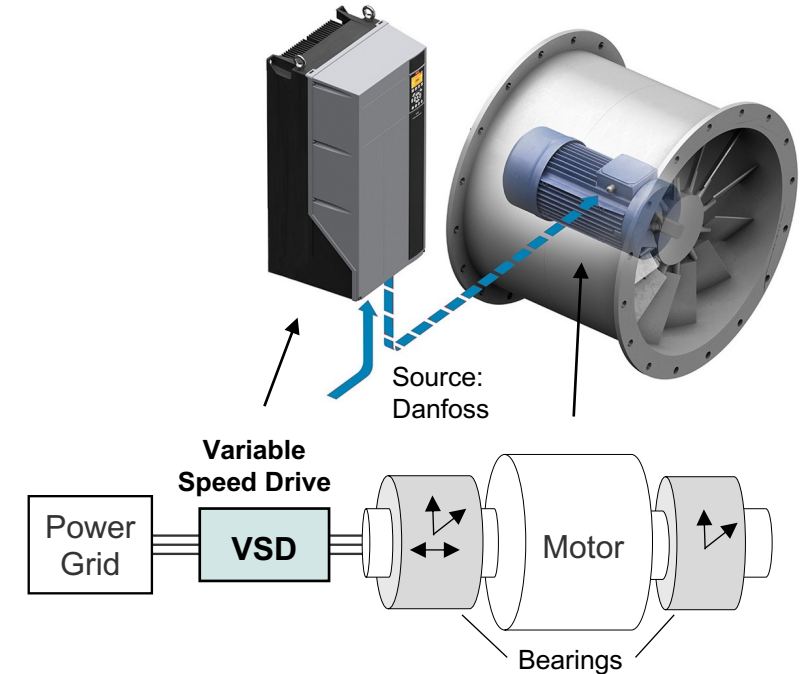
**Variable Speed Drive (VSD) potential energy savings: 115 TWh/year**

>11% of US electricity!

Per DOE: VSDs are cost effective in >75% of systems, but only adopted in 10%.

**Why?**

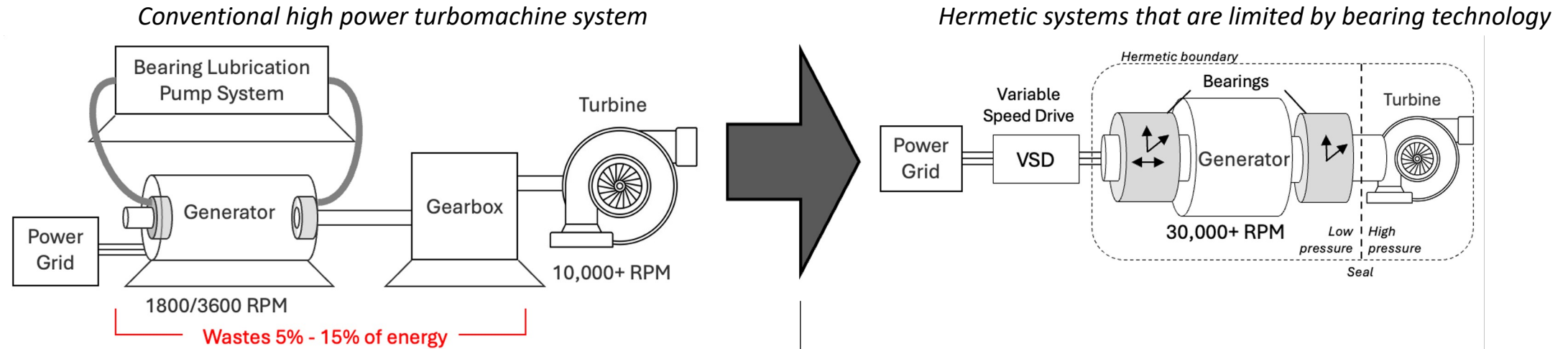
## Limited Reliability



- ➔ VSDs increase motor failure rates by 3x
- ➔ 60% of motor failures due to bearings

# Problem: Closed Brayton Cycles Limited By Bearings

Need for cost-effective bearings that operate in hermetic environment



- Large size → *compromises the power density advantages of fluids like sCO<sub>2</sub>*
- High cost → *dry gas seals*
- Maintenance, reliability concerns

- Compact and highly integrated
- Needs oil-free bearings
  - Gas: foil or externally pressurized
  - Maglev
- Current technology has shortcomings

# Today's Hermetic Bearing Solutions

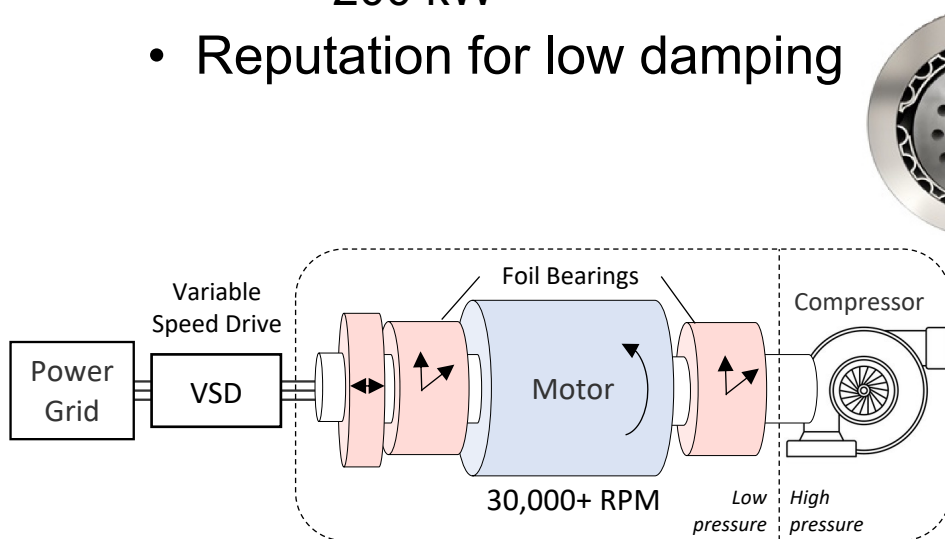
## Gas Foil

- **Benefits**

- Completely passive operation
- No pass-throughs into cavity

- **Challenges**

- Wear during start/stop
  - Limits maximum shaft weight / lifetime
  - < 200 kW
- Reputation for low damping



Source: Sulzer

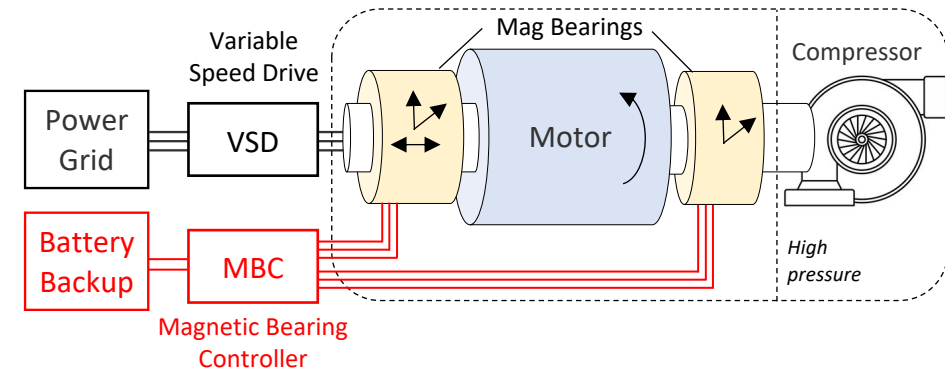
## Active Magnetic

- **Benefits**

- Works for large shafts
- Excellent vibration / acoustics
- System health monitoring

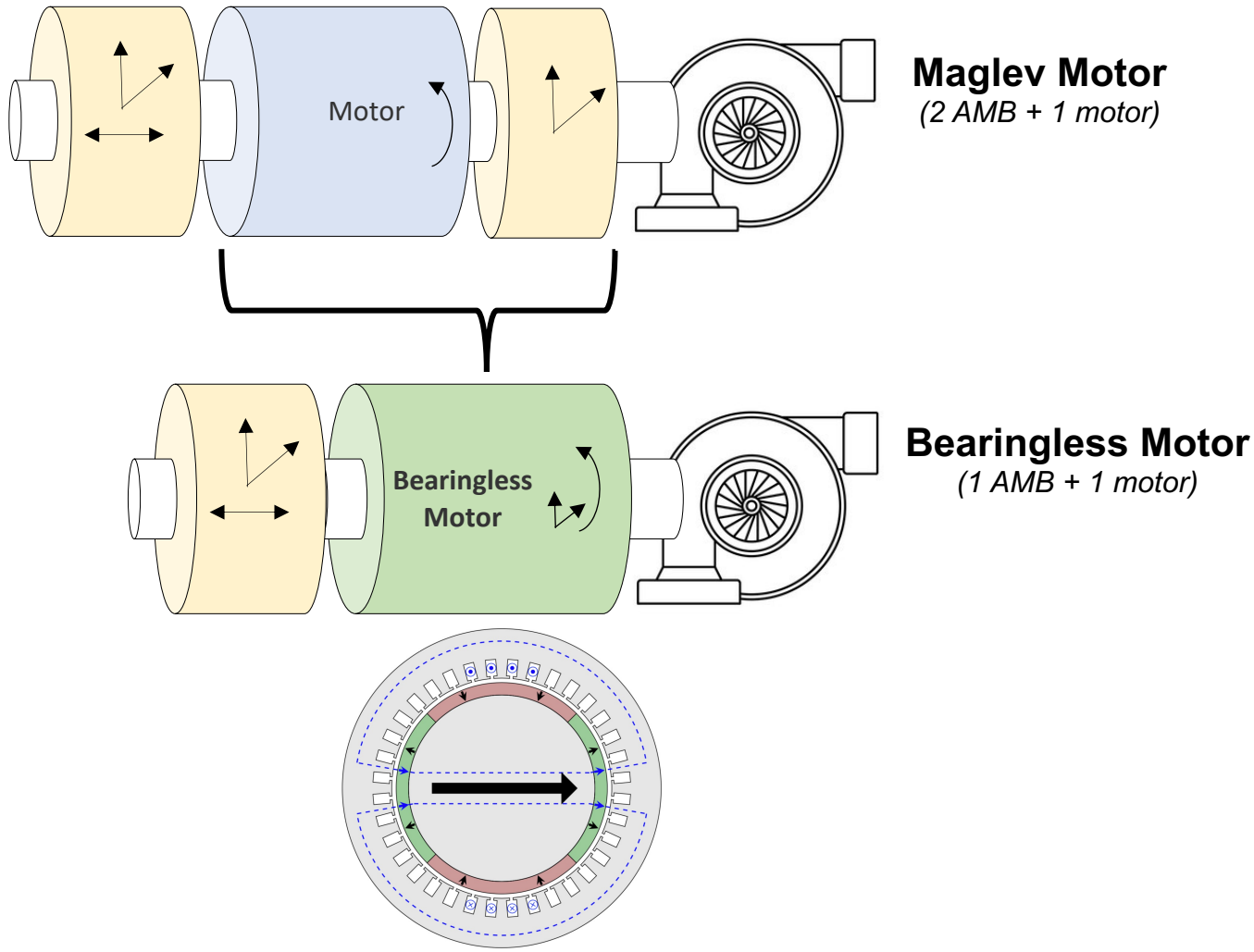
- **Challenges**

- High cost
- Increased axial shaft length
- Large number of passthroughs



# Our Solution: Bearingless Motors

Motor technology that controls magnetic forces on shaft



## Technology:

- Standard motor + new winding
- Standard VFD
- No performance degradation
- Support rotor weight with 5% power reduction

AMB: Active Magnetic Bearing



# Status: Benchtop Demonstrations Complete

## Bearingless PM Machines

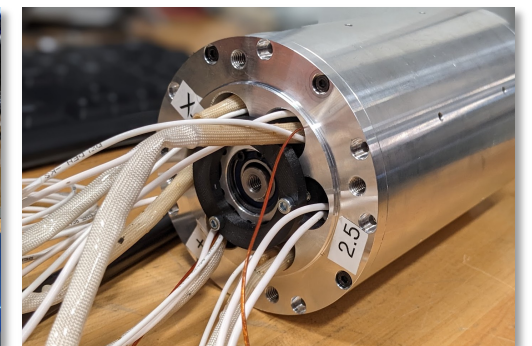
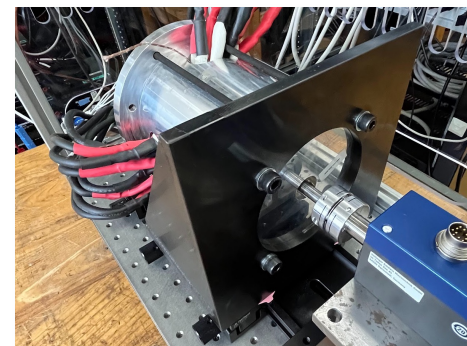
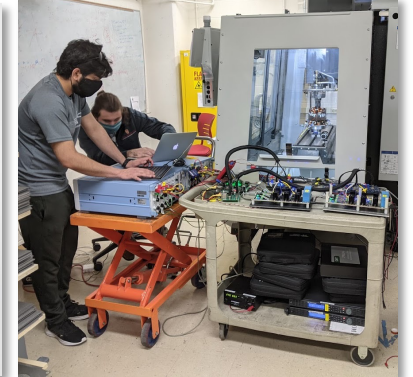
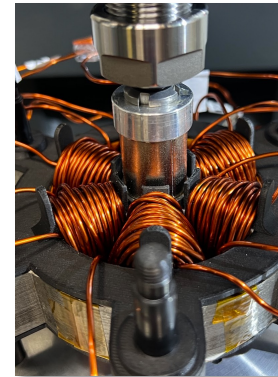
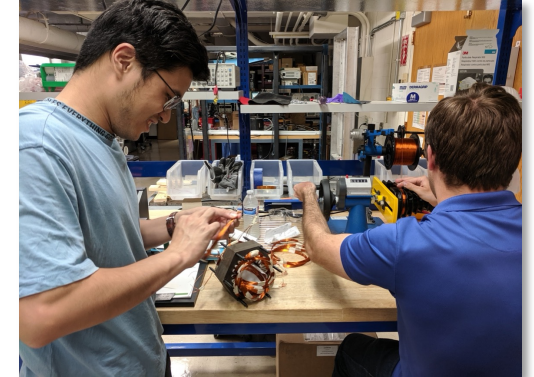
1. 1 kW, 30,000 r/min Motor
2. 10 kW, 160,000 r/min Motor
3. 3.4 kW, 35,000 r/min “Twin” Motor
4. 13 kW, 140,000 r/min “Twin” Motor
5. 50 kW, 80,000 r/min Generator
6. 13 kW, 160,000 r/min Motor + foil bearings

## Bearingless Induction Machines

7. 3.6 kW, 30,000 r/min Motor

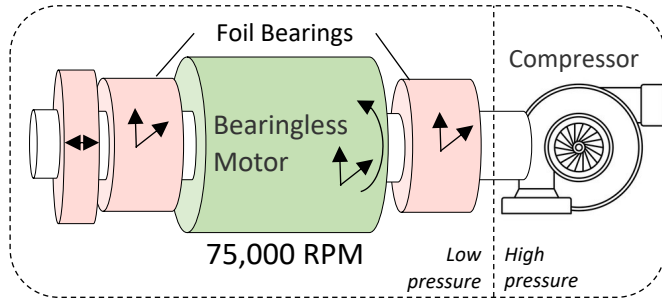
## AC Homopolar Machines *(for flywheels)*

8. 1 kW, 3,600 r/min Motor
9. 6 kW, 10,000 r/min Motor/Generator



# Status: Upcoming Application-Scale Demonstrations

## Assisting Foil Bearings



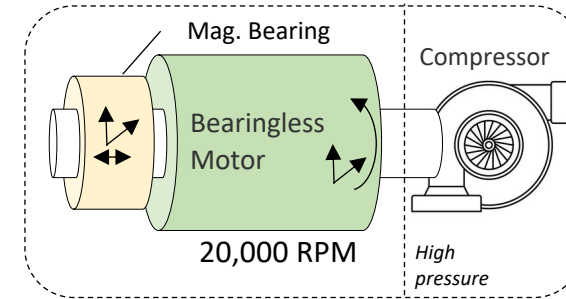
**Create radial shaft forces to enable foil bearing use for large shafts**

- Low cost
- Few components and passthroughs

### Planned demonstration unit

- 100 kW
- 75 kRPM
- sCO<sub>2</sub> turbomachine from Sandia Brayton Lab

## Removing Magnetic Bearings



**Use bearingless motor to eliminate a magnetic bearing actuator**

- Largest shafts
- Best rotor dynamics

### Planned demonstration unit

- 200 kW
- 20 kRPM
- Dyno testing planned for spring 2026

# Next Steps: Looking for Partners!

- Basic science figured out
- Focus on customization and demonstration
- Looking for collaborators
  - Application scale demonstrations
  - SBIR/STTR proposals
- Goal: commercialization

**Interested in learning more? Contact us:**

Eric Severson

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